Feedforward/Feedback Structure
Tuning Feedforward Control

Trial 1
\( \tau_1 = 1, \tau_2 = 0.5 \)

(a) Corrective action is too slow

Trial 2
\( \tau_1 = 2, \tau_2 = 0.5 \)

(b) Now \( \tau_1 - \tau_2 \) is satisfactory

Trial 3
\( \tau_1 = 2.5, \tau_2 = 1.0 \)

(c) Satisfactory control